These are the final exam questions (starting from next page) of the course. Here is the instructions for sending your solutions after downloading this file.

- S1. Print this document
- S2. Write your solution steps clearly in the space provided.
- S3. Scan your solution papers and save as pdf file
 named ep208-fin-yourIdNo.pdf
 such as ep208-fin-12345691.pdf
- S4. Send the file to Email Address bingul@gantep.edu.tr
- S5. Subject (konu) of your email must be ep208 fin yourIdNo

Deadline date / time : 18 June 2023 / 13:00

If you do not obey one of the rules above, your paper won't be considered as an exam paper!

Good Luck, Prof. Dr. Ahmet Bingül

Fill in the blanks below:

| Name | : |
|--------------|---|
| Surname | : |
| Studen ID No | : |

Signature :

(25 %) Evaluate the following integral:

$$\int_{-2}^{2} \frac{\sin(x)}{x} dx$$

(a) by using analytical method

(c) Write a C++ or MATLAB program by using Simpson's Method with n = 1000 parts.

(b) Use int() function MATLAB to compare your results.

(25 %) Find the root of the equation $\cos(2x) = x^2$

(a) by using fzero() function in MATLAB

(b) by using Newton-Raphson Method with tolerance = 0.01. Do not write computer program. Solution has to be performed manually.

(25 %) 3. A ball of mass m = 0.6 kg and radius r = 0.1 m is fired up with an angle of $\theta = 32^{\circ}$ and with an initial speed of $v_0 = 50$ m/s. Assume that the drag coefficient is given by $C_d = 0.2$, and air density is $\rho = 1.2$ kg/m³ and g = 9.8 m/s².



(a) Write down the equations of motion both in x and y directions and Cromer-Euler steps for the numerical solution.

(b) Write a C++ or MATLAB program to estimate its maximum height (*H*) and maximum range (*R*) of the ball for $h = \Delta t = 0.01$ s. Write down program's output.

(25 %) 4. Time (*t*) vs velocity (v) data of a drone moving upward direction is collected as follows:



t(s) | 0.2 0.4 0.6 0.8 1.0 1.2 1.4 1.6 v(m/s) | 3.1 4.0 5.1 6.0 6.9 8.1 9.0 9.8

Write C++ or MATLAB program to determine the initial of speed of the drone at t = 0 using Linear Least Square Fitting Method. Do not use cftool. Write down the output of your program.